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Department of the Navy OFFICE OF NAVAL RESEARCH Structural Mechanics Program Arlington, Virginia 22217

Contract N00014-78-C-0647
Project NR 064-609
Technical Repet, No. 11

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Report 0U-AMNE-80-2, TR-11

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OF BIMODULUS COMPOSITE MATERIALS.

by

10 C.W./Bert, J.N./Reddy, V. Sudhakar/Reddy W.C./Chao

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School of Aerospace, Mechanical and Nuclear Engineering University of Oklahoma Norman, Oklahoma 73019

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# ANALYSIS OF THICK RECTANGULAR PLATES LAMINATED OF BIMODULUS COMPOSITE MATERIALS

C.W. Bert\*, J.N. Reddy<sup>†</sup>, V. Sudhakar Reddy<sup>‡</sup>, and W.C. Chao<sup>‡</sup> University of Oklahoma, Norman, OK

A mixed finite-element analysis is presented for static behavior of rectangular plates having finite transverse shear moduli
and different elastic properties depending upon whether or not the
fiber-direction strains are tensile or compressive. As a benchmark
to evaluate the validity and accuracy of the finite-element analysis,
a closed-form solution is presented for the particular case of an
unsymmetric-cross-ply plate having freely supported edges and subjected to a sinusoidally distributed normal-pressure loading.

The research reported here was sponsored by the Office of Naval Research, Structural Mechanics Program.

Index categories: Aircraft Structural Materials; Structural Composite Materials; Structural Static Analysis.

<sup>\*</sup> Benjamin H. Perkinson Professor of Engineering, School of Aerospace, Mechanical and Nuclear Engineering, Associate Fellow AIAA.

<sup>†</sup> Associate Professor, School of Aerospace, Mechanical and Nuclear Engineering.

F Graduate Research Assistant, Mechanical Engineering

#### Nomenclature

A,A $_{ij}$  = stretching stiffnesses for transversely isotropic and crossply orthotropic plates

a,b = plate dimensions in x and y directions

 $B,B_{ij}$  = bending-stretching coupling stiffnesses for transversely isotropic and cross-ply orthotropic plates

 $C_{rs}$  = coefficients defined in Eqs. (15)

D,D<sub>ij</sub> = bending stiffnesses for transversely isotropic and cross-ply orthotropic plates

 $q^{x} = 9()/9x$ 

E<sub>c</sub>,E<sub>t</sub> = compressive and tensile Young's moduli for transversely isotropic bimodulus material

 $E_f, E_m$  = fiber and matrix Young's moduli

 $E_1, E_2, E_3$  = Young's moduli in directions x,y,z

 $F_i^{\alpha}$  = generalized force components defined in Eqs. (20)

 $G_{13}$ ,  $G_{23}$  = longitudinal-thickness and transverse-thickness shear moduli of orthotropic material

 $G_{zc}$ ,  $G_{zt}$  = thickness-shear moduli for transversely isotropic bimodulus material

h = total thickness of plate

K = shear-correction coefficient for transversely isotropic plate

 $K_4$ ,  $K_5$  = shear-correction coefficients for cross-ply orthotropic plate

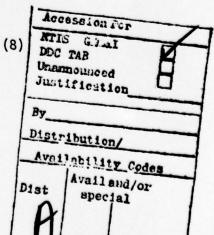
K<sub>i,j</sub> = matrix coefficients defined in Eqs. (20)

L<sub>rs</sub> = linear differential operators defined in Eqs. (8)

 $M_i, N_i$  = stress couples and inplane stress resultants

N<sub>i</sub> = interpolation function at node i

n = number of nodes per element



 $\mathbf{Q_c}, \mathbf{Q_t}$  = compressive and tensile plane-stress-reduced stiffnesses for isotropic bimodulus material

 $Q_x, Q_v$  = thickness-shear stress resultants

 $\bar{Q}_{,\Delta}Q = (1/2)(Q_{c}+Q_{t}), Q_{c} - Q_{t}$ 

Q<sub>i,ik2</sub> = plane-stress-reduced stiffnesses for orthotropic bimodulus material

q,q<sub>o</sub> = normal pressure and its peak value

s,S<sub>ij</sub> = thickness-shear stiffnesses for transversely isotropic and crossply orthotropic plates

 $s_{i,j}$  = matrix coefficients defined in Eqs. (20)

U,V,W = midplane displacement coefficients (amplitudes of  $u^0, v^0, w^0$ )

u,v,w = displacements in x,y,z directions

 $u^{0}, v^{0}, w^{0}$  = midplane displacements in x,y,z directions

 $V_f, V_f^*$  = fiber volume fraction and effective fiber volume fraction

X,Y = bending-slope coefficients (amplitudes of  $\psi_x, \psi_y$ )

x,y,z = plate coordinates in longitudinal, transverse, and downward thickness directions

 $Z_{x}, Z_{y} = z_{n}/h, z_{nx}/h, z_{ny}/h$ 

z<sub>n</sub> = neutral-surface position for isotropic square plate

 $z_{nx}, z_{ny}$  = neutral-surface positions associated with  $\varepsilon_x$  =0 and  $\varepsilon_y$  =0

 $\alpha,\beta$  =  $\pi/a$ ,  $\pi/b$ 

 $\epsilon_{ij}, \epsilon_{ij}^{0}$  = strain component at arbitrary location and at midplane

k,j = curvature component

 $v_f, v_m$  = fiber and matrix Poisson's ratios

 $v_{12}, v_{23}$  = major (longitudinal-transverse) and transverse-thickness Poisson's ratios

σ<sub>i</sub> = stress component

 $\phi_{e}, \phi_{e}^{i}$  = typical variable in general and its value at node i

 $\psi_{x}, \psi_{y}$  = bending slopes in xz and yz planes

(), x = 9()/9x

#### Subscripts:

i,j = 1,2,6 contracted indices

k = 1(t or tension), 2(c or compression)

layer number

#### Introduction

The increasing use of composite materials in structures has led to the requirement of more realistic mathematical modeling of the material behavior and incorporation of this more realistic model into structural analyses. It has been found that certain fiber-reinforced materials, especially those with very soft matrices (for example, cord-rubber composites), exhibit quite different elastic behavior depending upon whether the fiber-direction strain is tensile or compressive<sup>1-3</sup>. As a first approximation, the stress-strain behavior of such materials is often represented as being bilinear, with different slopes (elastic properties) depending upon the sign of the fiber-direction strain. Such a material is called a bimodulus composite material, and it has been shown that the fiber-governed symmetric-compliance model proposed in Ref. 4 agrees well with experimental data for several materials with drastically different elastic properties in tension and compression.

To the best of the present investigators' knowledge, the only previous analyses of plates laminated of bimodulus composite materials are all limited to thin plates. Jones and Morgan<sup>5</sup> considered cylindrical bending of a finite-width cross-ply strip; Kincannon et al.<sup>6</sup> considered cross-ply elliptic plates. Rectangular plates were treated by Bert et al.<sup>7</sup> using a closed-form solution

and by Reddy<sup>8</sup> using mixed finite elements.

Apparently the only previous analyses involving thick plates of bimodulus material are those of Shapiro<sup>9</sup> using a stress-function elasticity approach for isotropic circular plates and of Kamiya<sup>10</sup> using an energy approach for cylindrical bending of finite-width isotropic strips.

Of course, for thick plates laminated of ordinary (not bimodulus) materials, there have been a number of analyses, such as those of Whitney<sup>11</sup>, Whitney and Pagano<sup>12</sup>, and Turvey<sup>13</sup>, for example.

The analyses presented here are believed to be the very first analyses of thick plates that are finite in two directions and laminated of bimodulus composite materials.

#### Formulation

The basic theory of laminated anisotropic thick plates used by Whitney and Pagano<sup>12</sup> is an extension of Reissner's theory for isotropic plates<sup>14</sup>. It is based upon the following assumed displacement field:

$$u(x,y,z) = u^{0}(x,y) + z\psi_{x}(x,y)$$

$$v(x,y,z) = v^{0}(x,y) + z\psi_{y}(x,y)$$

$$w(x,y,z) = w^{0}(x,y)$$
(1)

Here x,y are rectangular coordinates in the plane of the plate, z is the thickness-direction coordinate measured downward from the midplane of the plate; u,v,w are the displacements in the respective x,y,z directions;  $u^0$ ,  $v^0$ ,  $w^0$  are the corresponding midplane displacements; and  $\psi_x$  and  $\psi_y$  are the slopes in the xz and yz planes due to bending only.

Neglecting body forces, body moments, and surface shearing forces, the equations of equilibrium can be written as

$$N_{1,x} + N_{6,y} = 0$$
;  $N_{6,x} + N_{2,y} = 0$   
 $Q_{x,x} + Q_{y,y} + q = 0$ ;  $M_{6,x} + M_{2,y} - Q_y = 0$   
 $M_{1,x} + M_{6,y} - Q_x = 0$  (2)

Here q is the normal pressure, ( ), denotes  $\theta$ ( )/ $\theta$ x, and

$$(N_{i}, M_{i}) = \int_{-h/2}^{h/2} (1, z)\sigma_{i} dz$$
 (i=1,2,6)   
 
$$(Q_{y}, Q_{x}) = \int_{-h/2}^{h/2} (\sigma_{4}, \sigma_{5}) dz$$
 (3)

Here h is the plate (laminate) thickness, and the so-called contracted subscript notation is employed to denote the stress components. Thus,  $\sigma_1$  and  $\sigma_2$  are inplane normal stresses in the x and y directions;  $\sigma_6$  is the inplane shear stress associated with the x,y axes; and  $\sigma_4$  and  $\sigma_5$  are the thickness shear stresses in the yz and xz planes.

Assuming that the only plane of symmetry existing is in the plane of the plate, the plate constitutive relations can be written as

$$\begin{Bmatrix}
N_{i} \\
M_{i}
\end{Bmatrix} = \begin{bmatrix}
A_{ij} & B_{ij} \\
B_{ij} & D_{ij}
\end{bmatrix}
\begin{Bmatrix}
\varepsilon_{j} \\
\kappa_{j}
\end{Bmatrix} (i,j=1,2,6)$$

$$\begin{Bmatrix}
Q_{y} \\
Q_{x}
\end{Bmatrix} = \begin{bmatrix}
K_{4}^{2}S_{44} & K_{4}K_{5}S_{45} \\
K_{4}K_{5}S_{45} & K_{5}^{2}S_{55}
\end{bmatrix}
\begin{Bmatrix}
\varepsilon_{4} \\
\varepsilon_{5}
\end{Bmatrix}$$
(4)

The  $A_{ij}$ ,  $B_{ij}$ ,  $D_{ij}$ ,  $S_{ij}$  are the respective inplane, bending-inplane coupling, bending or twisting, and thickness-shear stiffnesses defined as follows:

Here  $Q_{ijkl}$  denotes the plane-stress reduced stiffness, where ij refers to the position in the stress-strain-relation array (analogous to Eqs. (4)), k refers to the sign of the fiber-direction strain (1  $\sim$  +, 2  $\sim$  -), and  $\ell$  is the layer number.

The linear equations for the kinematics of deformation are

$$\varepsilon_{1}^{0} = u_{,\chi}; \quad \varepsilon_{2}^{0} = v_{,y}; \quad \varepsilon_{6}^{0} = u_{,y} + v_{,\chi}$$

$$\kappa_{1} = \psi_{\chi,\chi}; \quad \kappa_{2} = \psi_{y,y}; \quad \kappa_{6} = \psi_{\chi,y} + \psi_{y,\chi}$$

$$\varepsilon_{4} = w_{,y} + \psi_{y}; \quad \varepsilon_{5} = w_{,\chi} + \psi_{\chi}$$
(6)

Equations (1)-(6) plus those of Appendix A constitute the appropriate theory, in differential-equation form, for the class of plates considered here (linear, thick, laminated, anisotropic, bimodulus).

#### Closed-Form Solution for Cross-Ply Laminate

Here we consider the particular case of a cross-ply laminate, i.e., one in which some of the layers are oriented along the x axis and the remainder along the y axis. Then the terms with subscripts 16, 26, and 45 vanish from the symmetric arrays in Eqs. (4). For bimodulus-material cross-ply laminates, Eqs. (5) integrate as indicated in Appendix A and depend upon the neutral-surface locations,  $Z_x$  and  $Z_y$ , as well as the  $Q_{ijk\ell}$ .

If it is tentatively assumed that the neutral-surface locations are independent of x and y, Eqs. (2), (4), and (6) can be combined to yield the following governing equations in terms of the midplane displacements ( $u^0, v^0, w^0$ ) and bending slopes ( $\psi_y$  and  $\psi_x$ ):

$$[L_{rs}]\{u^{0}, v^{0}, w^{0}, \psi_{y}, \psi_{x}\}^{T} = \{0, 0, q, 0, 0\}^{T}$$
 (7)

where  $[L_{rs}]$  is a symmetric linear differential operator matrix with the following elements:

$$\begin{split} L_{11} &= A_{11}d_{X}^{2} + A_{66}d_{y}^{2} \; ; \; L_{12} = (A_{12}+A_{66})d_{X}d_{y} \; ; \; L_{13} = 0 \; ; \\ L_{14} &= (B_{12}+B_{66})d_{X}d_{y} \; ; \; L_{15} = B_{11}d_{X}^{2} + B_{66}d_{y}^{2} \; ; \; L_{22} = A_{66}d_{X}^{2} + A_{22}d_{y}^{2} \; ; \\ L_{23} &= 0 \; ; \; L_{24} = B_{66}d_{X}^{2} + B_{22}d_{y}^{2} \; ; \; L_{25} = L_{14} \; ; \; L_{33} = - K_{5}^{2}S_{55}d_{X}^{2} - K_{4}^{2}S_{44}d_{y} \; ; \; L_{35} = - K_{5}^{2}S_{55}d_{X} \; ; \\ L_{44} &= D_{66}d_{X}^{2} + D_{22}d_{y}^{2} - K_{4}^{2}S_{44} \; ; \; L_{45} = (D_{12}+D_{66})d_{X}d_{y} \; ; \\ L_{55} &= D_{11}d_{X}^{2} + D_{66}d_{y}^{2} - K_{5}^{2}S_{55} \; ; \; d_{X} = \partial(-)/\partial x \; ; \; dy = \partial(-)/\partial y \end{split}$$

For a plate hinged flexurally, but free to move in a direction normal to each edge, the boundary conditions are

$$N_{1}(0,y) = N_{1}(a,y) = 0 ; u^{0}(x,0) = u^{0}(x,b) = 0$$

$$v^{0}(0,y) = v^{0}(a,y) = 0 ; N_{2}(x,0) = N_{2}(x,b) = 0$$

$$w^{0}(0,y) = w^{0}(a,y) = 0 ; w^{0}(x,0) = w^{0}(x,b) = 0$$

$$\psi_{y}(0,y) = \psi_{y}(a,y) = 0 ; M_{2}(x,0) = M_{2}(x,b) = 0$$

$$M_{1}(0,y) = M_{1}(a,y) = 0 ; \psi_{x}(x,0) = \psi_{x}(x,b) = 0$$
(9)

The criteria that the neutral-surface locations associated with the  ${\sf x}$  and  ${\sf y}$  directions remain constant are as follows:

$$\varepsilon_1^0 + z_{nx}^{\kappa_1} = 0 \; ; \; \varepsilon_2^0 + z_{ny}^{\kappa_2} = 0$$
 (10)

or

$$z_{nx} = -\epsilon_1^0/\kappa_1 = -u_{,x}^0/\psi_{x,x}$$

$$z_{ny} = -\epsilon_2^0/\kappa_2 = -v_{,y}^0/\psi_{y,y}$$
(11)

The normal-pressure loading is taken to be sinusoidally distributed as

$$q = q_0 \sin \alpha x \sin \beta y$$
 (12)

where  $\alpha \equiv \pi/a$  ,  $\beta \equiv \pi/b$ .

The governing equations (7) with pressure distribution given by Eq. (12), boundary conditions (9), and neutral-surface location criteria (11) are all satisfied exactly in closed form by the following set of functions.

$$u^{0} = U \cos \alpha x \sin \beta y$$

$$v^{0} = V \sin \alpha x \cos \beta y$$

$$w^{0} = W \sin \alpha x \sin \beta y$$

$$\psi_{y} = Y \sin \alpha x \cos \beta y$$

$$\psi_{x} = X \cos \alpha x \sin \beta y$$
(13)

Then differential equation set (7) reduces to algebraic form as follows:

$$[c_{rs}]\{U,V,W,Y,X\}^T = \{0,0,q_0,0,0\}^T$$
 (14)

Here  $[C_{rs}]$  is a symmetric matrix with coefficients

$$C_{11} = A_{11}\alpha^{2} + A_{66}\beta^{2} ; C_{12} = (A_{12}+A_{66})\alpha\beta ; C_{13} = 0 ;$$

$$C_{14} = (B_{12}+B_{66})\alpha\beta ; C_{15} = B_{11}\alpha^{2} + B_{66}\beta^{2} ;$$

$$C_{22} = A_{66}\alpha^{2} + A_{22}\beta^{2} ; C_{23} = 0 ; C_{24} = B_{66}\alpha^{2} + B_{22}\beta^{2} ;$$

$$C_{25} = C_{14} ; C_{33} = K_{5}^{2}S_{55}\alpha^{2} + K_{4}^{2}S_{44}\beta^{2} ; C_{34} = K_{4}^{2}S_{44}\beta ;$$

$$C_{35} = K_{5}^{2}S_{55}\alpha ; C_{44} = D_{66}\alpha^{2} + D_{22}\beta^{2} + K_{4}^{2}S_{44} ;$$

$$C_{45} = (D_{12}+D_{66})\alpha\beta ; C_{55} = D_{11}\alpha^{2} + D_{66}\alpha^{2} + K_{5}^{2}S_{55}$$

#### Finite-Element Analysis

Here we present a mixed finite-element model associated with Eqs. (1)-(4) governing the bending of laminated, thick composite plates. The word "mixed" implies that independent approximations are used for all of the variables,  $u,v,w,\psi_{\chi}$ , and  $\psi_{\chi}$ . Using the thin-plate equations of layered composite plates, and treating

$$w_{,x} + \psi_{x} = 0$$
 ,  $w_{,y} + \psi_{y} = 0$  (16)

as constraints, Reddy<sup>17</sup> presented a variational formulation of Eqs. (1)-(4). That is, the thick-plate theory can be interpreted as one resulting from the thin-plate theory by treating the slope-displacement relations as constraints. The Lagrange multipliers associated with these constraints are found to be the thickness-shear stress resultants,  $Q_X$  and  $Q_y$ . The model described here is essentially the same as in Ref. 17.

Suppose that the region occupied by the plate is given by  $\Omega X(-h/2,h/2)$ , where  $\Omega$  denotes the middle plane (x-y). As noted earlier, the thickness direction is integrated into the coefficients,  $A_{ij}$ ,  $B_{ij}$ , and  $D_{ij}$ . Hence, we divide the plate into a finite number of elements, denoted by  $\Omega_e$ . Over each element  $\Omega_e$ , we assume that the variables  $u,v,w,\psi_X$ , and  $\psi_Y$  are interpolated by expressions of the form

$$\phi^{e} = \sum_{i}^{n} N_{i} \phi_{e}^{i}$$
 (17)

where  $\phi^e$  denotes the restriction of a typical variable to  $\Omega_e$ ,  $\phi_e^i$  its value at node i (of element  $\Omega_e$ ), and  $N_i$  are the linearly independent interpolation functions associated with the typical element. Since we are concerned here with rectangular plates, the typical element is chosen to be the four-node (n=4) quadrilater all element of the serendipity family.

Substituting expressions of the form (17) for u,v,w, $\psi_X$ , and  $\psi_y$  into the total potential energy associated with the case of a cross-ply laminate

$$\frac{1}{2} \int_{\Omega} \left\{ A_{11} \left( \frac{\partial u}{\partial x} \right)^{2} + A_{66} \left( \frac{\partial u}{\partial y} \right)^{2} + 2A_{12} \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + 2A_{66} \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + A_{22} \left( \frac{\partial v}{\partial y} \right)^{2} \right. \\
+ A_{66} \left( \frac{\partial v}{\partial y} \right)^{2} + \frac{\partial u}{\partial x} \left( B_{11} \frac{\partial v}{\partial x} + B_{12} \frac{\partial v}{\partial y} \right) + B_{66} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \left( \frac{\partial v}{\partial y} + \frac{\partial v}{\partial x} \right) \\
+ \frac{\partial v}{\partial y} \left( B_{12} \frac{\partial v}{\partial x} + B_{22} \frac{\partial v}{\partial y} \right) + \frac{\partial v}{\partial x} \left( B_{11} \frac{\partial u}{\partial x} + B_{12} \frac{\partial v}{\partial y} \right) + B_{66} \left( \frac{\partial v}{\partial y} + \frac{\partial v}{\partial x} \right) \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \\
+ \frac{\partial v}{\partial y} \left( B_{12} \frac{\partial u}{\partial x} + B_{22} \frac{\partial v}{\partial y} \right) + D_{11} \left( \frac{\partial v}{\partial x} \right)^{2} + D_{66} \left( \frac{\partial v}{\partial y} \right)^{2} \\
+ 2D_{12} \frac{\partial v}{\partial x} \frac{\partial v}{\partial y} + 2D_{66} \frac{\partial v}{\partial y} \frac{\partial v}{\partial x} + D_{22} \left( \frac{\partial v}{\partial y} \right)^{2} + D_{66} \left( \frac{\partial v}{\partial x} \right)^{2} + A_{55} \left( \frac{\partial w}{\partial x} + v_{x} \right)^{2} \\
+ A_{44} \left( \frac{\partial w}{\partial y} + v_{y} \right)^{2} \right\} dx dy + \int_{\Omega} q_{w} dx dy \tag{18}$$

we obtain, for each element,

$$[K^{e}]\{\Delta^{e}\} = \{F^{e}\}$$
 (19) where  $\{\Delta^{e}\} = \{u_{i}^{e}, v_{i}^{e}, w_{i}^{e}, \psi_{xi}^{e}, \psi_{yi}^{e}\}^{T}$ , and

$$K_{ij}^{1} = A_{11}S_{ij}^{X} + A_{66}S_{ij}^{Y}, \quad K_{ij}^{12} = A_{12}S_{ij}^{XY} + A_{66}S_{ji}^{XY}$$

$$K_{ij}^{13} = 0, \quad K_{ij}^{14} = B_{11}S_{ij}^{X} + B_{66}S_{ij}^{Y}, \quad K_{ij}^{15} = B_{12}S_{ij}^{XY} + B_{66}S_{ji}^{XY}$$

$$K_{ij}^{22} = A_{22}S_{ij}^{Y} + A_{66}S_{ij}^{X}, \quad K_{ij}^{23} = 0, \quad K_{ij}^{24} = B_{66}S_{ij}^{XY} + B_{12}S_{ji}^{XY}$$

$$K_{ij}^{25} = B_{66}S_{ij}^{X} + B_{22}S_{ij}^{Y}, \quad K_{ij}^{33} = A_{55}S_{ij}^{X} + A_{44}S_{ij}^{Y}, \quad K_{ij}^{34} = A_{55}S_{ij}^{XO}$$

$$K_{ij}^{35} = A_{44}S_{ij}^{YO}, \quad K_{ij}^{44} = D_{11}S_{ij}^{X} + D_{66}S_{ij}^{Y} + A_{55}S_{ij}^{O}$$

$$K_{ij}^{45} = D_{12}S_{ij}^{XY} + D_{66}S_{ji}^{XY}, \quad K_{ij}^{55} = D_{66}S_{ij}^{X} + D_{22}S_{ij}^{Y} + A_{44}S_{ij}^{O}$$

$$F_{i}^{3} = \int_{\Omega_{e}} qN_{i} \, dx \, dy, \quad F_{i}^{\alpha} = 0, \quad \alpha = 1,2,4,5, \quad A_{\alpha\beta} = K_{\alpha}K_{\beta} \, S_{\alpha\beta}, \quad (\alpha,\beta=4,5)$$

$$S_{ij}^{\xi\eta} = \int_{\Omega_{e}} N_{i,\xi} \, N_{j,\eta} \, dx \, dy \, (\xi,\eta=0,x,y), \quad S_{ij}^{O} = S_{ij}^{OO}$$

$$(20)$$

The element equations (19) are assembled in the usual manner, and boundary conditions are applied before solving the equations.

#### Numerical Results

As the first example, we take the case of a homogeneous (single-layer) plate of transversely isotropic bimodulus material. The plane of isotropy is assumed to coincide with the midplane of the plate, and the inplane Poisson's ratio is assumed to be zero. Then the closed-form solution reduces to the simplified form presented in Appendix B. Numerical results are presented in Tables 1 and 2.

Table 1. Comparison of Neutral-Surface Locations for Transversely Isotropic Square Plate

	Neutral	Neutral-Surface Location Z			
E <sub>t</sub> /E <sub>c</sub> =G <sub>zt</sub> /G <sub>zc</sub>	G <sub>zc</sub> /E <sub>c</sub> =0.1	0.3	0.5		
	Exact Clo	sed-Form Solut	ion:		
0.5	- 0.08578	- 0.08578	- 0.08578		
1.0	0	0	0		
2.0	+ 0.08578	+ 0.08578	+ 0.08578		
	Simplifie	d Approximate S	Solution:		
0.5	- 0.08579	- 0.08579	- 0.08579		
1.0	0	0	0		
2.0	+ 0.08579	+ 0.08579	+ 0.08579		
	Mixed Finite-Element Solution:				
0.5	- 0.08578	- 0.08578	- 0.08578		
1.0	0	0	0		
2.0	+ 0.08578	+ 0.08578	+ 0.08578		

Table 2. Comparison of Maximum Deflections for Transversely Isotropic Square Plate (h/b=0.1,  $K^2=5/6$ )

	Dimensionless Deflection WE <sub>c</sub> h <sup>3</sup> /q <sub>o</sub> b <sup>4</sup>			
E <sub>t</sub> /E <sub>c</sub> =G <sub>zt</sub> /G <sub>zc</sub>	$G_{zc}/E_{c}=0.1$	0.3	0.5	
	Exact Closed-Form Solution:			
0.5	0.05348	0.04774	0.04660	
1.0	0.03688	0.03283	0.03201	
2.0	0.02674	0.02387	0.02330	
	Simplified	d Approximat	e Solution:	
0.5	0.05004	0.04660	0.04591	
1.0	0.03445	0.03202	0.03153	
2.0	0.02530	0.02342	0.02296	
	Mixed Fin	ite-Element	Solution:	
0.5	0.05329	0.04743	0.04626	
1.0	0.03675	0.03261	0.03178	
2.0	0.02664	0.02371	0.02313	

It is noted that the middle-surface location is independent of  $\mathbf{G}_{zc}$  and  $\mathbf{G}_{zt}$ . The agreement among the results obtained by all three solutions is quite good.

As examples of some actual bimodulus materials, aramid-cord/rubber and polyester-cord/rubber are selected. The material properties used are listed in Table 3. The data are based on test results of Patel et al.<sup>3</sup>, using the data-reduction procedure of Model 2 in Ref. 4, except for the thickness-shear moduli, which were estimated as explained in Appendix C.

Table 3. Elastic Properties for Two Tire-Cord/Rubber, Unidirectional, Bimodulus Composite Materials  $^a$ 

	Aramid/Rubber		Polyester Rubber	
Property and Units	k=1	k=2	k=1	k=2
Longitudinal Young's modulus, GPa	3.58	0.0120	0.617	0.0369
Transverse Young's modulus, GPa	0.00909	0.0120	0.00800	0.0106
Major Poisson's ratio, dimensionless $^b$	0.416	0.205	0.475	0.185
Longitudinal-transverse shear modulus, ${\sf GPa}^c$	0.00370	0.00370	0.00262	0.00267
Transverse-thickness shear modulus, GPa	0.00290	0.00499	0.00233	0.00475

<sup>&</sup>lt;sup>a</sup>Fiber-direction tension is denoted by k=1, and fiber-direction compression by  $_{x}$  k=2.

k=2. It is assumed that the minor Poisson's ratio is given by the reciprocal relation

Numerical results for single-layer rectangular plates with the fibers oriented parallel to the x axis are given in Table 4, while those for cross-ply plates (stacking sequence as described in Appendix A) are listed in Table 5.

As can be seen in Tables 4 and 5, the agreement between the closed-form and finite-element results for both neutral-surface position and deflection is extremely good. Thus, it can be considered that the finite-element analysis has been soundly validated, and can now be used for more complicated combinations of loading, geometry, and boundary conditions not amenable to closed-form solutions.

It is noted that the aramid-rubber plates, in both the single-ply and cross-ply cases, have noticeably larger values of  $Z_{\rm X}$  than the polyester-rubber plates. This result is undoubtedly due to the more pronounced bimodulus effect in the fiber-direction Young's modulus of the aramid-rubber.

It is assumed that the longitudinal-thickness shear modulus is equal to this one.

Table 4. Neutral-Surface Positions and Dimensionless Deflections for Rectangular Plates of Single-Layer 0° Aramid-Rubber and Polyester-Rubber, as Determined by Two Different Methods (Thickness/Width, h/b=0.lt; K<sup>2</sup>=5/6)

Aspect Z <sub>x</sub>			z <sub>y</sub>		WE <sub>22c</sub> h <sup>3</sup> /q <sub>0</sub> b <sup>4</sup>		
Ratio	C.F*	F.E.	C.F*	F.E*	C.F*	F.E*	
	Aramid-Rubber:						
0.5	0.4453	0.4454	- 0.3304	- 0.3007	0.002544	0.002750	
0.6	0.4452	0.4452	- 0.2941	- 0.2734	0.004560	0.004827	
0.7	0.4447	0.4447	- 0.2564	- 0.2419	0.007393	0.007712	
0.8	0.4440	0.4440	- 0.2220	- 0.2117	0.01105	0.01140	
0.9	0.4431	0.4431	- 0.1923	- 0.1846	0.01545	0.01582	
1.0	0.4420	0.4420	- 0.1671	- 0.1614	0.02046	0.02083	
1.2	0.4394	0.4394	- 0.1285	- 0.1250	0.03160	0.03193	
1.4	0.4363	0.4363	- 0.1015	- 0.09919	0.04313	0.04335	
1.6	0.4328	0.4329	- 0.08228	- 0.08070	0.05406	0.05416	
1.8	0.4292	0.4294	- 0.06838	- 0.06724	0.06390	0.06388	
2.0	0.4253	0.4254	- 0.05813	- 0.05727	0.07250	0.07236	
			Polyest	er-Rubber:			
0.5	0.3044	0.3045	- 0.1597	- 0.1234	0.001529	0.001971	
0.6	0.3044	0.3045	- 0.1538	- 0.1245	0.002652	0.003265	
0.7	0.3042	0.3044	- 0.1426	- 0.1198	0.004283	0.005075	
0.8	0.3039	0.3041	- 0.1299	- 0.1124	0.006517	0.007487	
0.9	0.3035	0.3037	- 0.1174	- 0.1041	0.009421	0.01055	
1.0	0.3029	0.3031	- 0.1061	- 0.09586	0.01303	0.01430	
1.2	0.3015	0.3018	- 0.08728	- 0.08111	0.02223	0.02367	
1.4	0.2999	0.3001	- 0.07329	- 0.06941	0.03348	0.03492	
1.6	0.2979	0.2982	- 0.06296	- 0.06042	0.04574	0.04703	
1.8	0.2957	0.2960	- 0.05528	- 0.05356	0.05793	0.05897	
2.0	0.2934	0.2936	- 0.04959	- 0.04828	0.06925	0.07003	

<sup>\*</sup>C.F. denotes closed-form solution; F.E. signifies finite-element solution.

Table 5. Neutral-Surface Positions and Dimensionless Deflections for Rectangular Plates of Two-Layer Cross-Ply Aramid-Rubber and Polyester-Rubber, as Determined by Two Different Methods (Thickness/Width, h/b=0.1; K<sup>2</sup>=5/6)

Annest	z <sub>x</sub>		Z <sub>y</sub>		WE <sub>22c</sub> h <sup>3</sup> /q <sub>0</sub> b <sup>4</sup>	
Aspect Ratio	C.F.	F.E*	C.F*	F.E*	C.F*	F.E*
	Aramid-Rubber:					
0.5	0.4433	0.4431	- 0.06343	- 0.06223	0.002472	0.002576
0.6	0.4427	0.4426	- 0.05478	- 0.05443	0.004388	0.004518
0.7	0.4418	0.4418	- 0.04794	- 0.04778	0.007072	0.007220
0.8	0.4407	0.4407	- 0.04247	- 0.04237	0.01054	0.01070
0.9	0.4396	0.4396	- 0.03803	- 0.03795	0.01475	0.01490
1.0	0.4384	0.4384	- 0.03437	- 0.03430	0.01957	0.01972
1.2	0.4356	0.4356	- 0.02883	- 0.02860	0.03043	0.03054
1.4	0.4326	0.4325	- 0.02470	- 0.02477	0.04185	0.04190
1.6	0.4292	0.4292	- 0.02160	- 0.02165	0.05282	0.05280
1.8	0.4257	0.4256	- 0.01922	- 0.01923	0.06277	0.06264
2.0	0.4219	0.4219	- 0.01735	- 0.01734	0.07151	0.07137
			Polyest	er-Rubber:		
0.5	0.3650	0.3652	- 0.1285	- 0.1256	0.002539	0.002732
0.6	0.3644	0.3646	- 0.1178	- 0.1164	0.004527	0.004772
0.7	0.3638	0.3639	- 0.1097	- 0.1089	0.007288	0.007575
0.8	0.3631	0.3631	- 0.1036	- 0.1031	0.01078	0.01109
0.9	0.3622	0.3622	- 0.09886	- 0.09859	0.01487	0.01519
1.0	0.3613	0.3613	- 0.09526	- 0.09502	0.01933	0.01966
1.2	0.3593	0.3593	- 0.09001	- 0.09000	0.02846	0.02879
1.4	0.3571	0.3570	- 0.08660	- 0.08660	0.03674	0.03707
1.6	0.3546	0.3545	- 0.08430	- 0.08430	0.04356	0.04389
1.8	0.3519	0.3518	- 0.08267	- 0.08267	0.04890	0.04925
2.0	0.3491	0.3490	- 0.08150	- 0.08150	0.05301	0.05337

<sup>\*</sup>C.F. denotes closed-form solution; F.E. signifies finite-element solution.

Also, it is interesting to observe that there are only very slight differences in  $Z_{\chi}$  and deflection in going from a single layer to a cross-ply laminate. This is in contrast to the behavior of the polyester-rubber results and in considerable contrast to ordinary materials (which, of course have  $Z_{\chi}=0$  for the single-layer case). The most pronounced change in going from the single-layer to the two-layer case is the drastic decrease in  $Z_{\chi}$  for the aramid-rubber.

It should be cautioned that in the case of the closed-form solution, deflections due to various sinusoidally distributed loadings <u>cannot</u> be superimposed for bimodulus-material plates. The reason superposition is not valid here is that the necessary conditions for homogeneity of neutral-surface locations are not valid under superposition conditions, since, in general

$$Z_{n} = \frac{Z_{n}^{(1)} \psi_{x,x}^{(1)}(x,y) + Z_{n}^{(2)} \psi_{x,x}^{(2)}(x,y)}{\psi_{x,x}^{(1)}(x,y) + \psi_{x,x}^{(2)}(x,y)} \neq \text{constant}$$

even though  $Z_n^{(1)}$ ,  $Z_n^{(2)}$ , ... for the various individual Fourier components are constants. However, the finite-element solution is not subject to these limitations, since it provides for stepwise variation in neutral-surface location. Fig. 1 shows results for both sinusoidally and uniformly distributed loadings.

#### Concluding Remarks

Both finite-element and closed-form solutions have been found for thick, rectangular plates of single-layer and cross-ply laminates of bimodulus materials. Excellent agreement was obtained, and thus the finite-element formulation of this problem is considered to have been validated against an accurate benchmark.

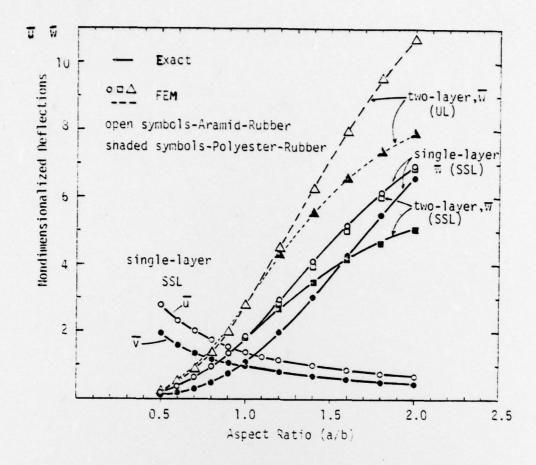


Fig. 1 Effect of plate aspect ratio on dimensionless displacements of aramid-rubber and polyester-rubber rectangular plates under uniform and sinusoidally distributed loadings (UL and SSL). Here  $\bar{w}=wE_{22}c^{h^3/q}o^{b^4}$  and  $\bar{u}=10^3 U/W$ .

The research reported here is currently being extended to (1) thermal bending due to changes in midplane temperature and in gradient through the thickness, and (2) free vibration.

#### <u>Acknowledgments</u>

The authors are grateful to the Office of Naval Research for financial support through Contract NO0014-78-C-0647 and to the University's Merrick Computing Center for providing computing time.

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### Appendix A: <u>Derivation of the Plate Stiffnesses for a Two-</u> Layer Cross-Ply Laminate of Bimodulus Material

In laminates containing bimodulus materials, the results of evaluating the integrals for the plate stiffnesses, Eqs. (5), are more complicated than those for ordinary-material laminates, since the individual-layer planestress-reduced stiffnesses depend upon the neutral-surface location. Here we derive the expressions for the case of a two-layer, cross-ply laminate. Each layer has the same thickness and the same bimodulus orthotropic elastic properties with respect to the fiber direction. The bottom layer is denoted as layer 1, i.e.,  $\ell = 1$  in  $Q_{ijk\ell}$ , is oriented in the x direction, and occupies the thickness-direction interval from z = 0 to z = h/2, where z is measured position downward from the midplane. The top layer ( $\ell=2$ ) is oriented in the y direction and is located from z = -h/2 to z = 0. In the case considered, it is assumed that the upper portion of the top layer ( $\ell=2$ ) is in compression  $(k=2 \text{ in } Q_{ijk})$  in the fiber direction and that the lower portion of the top layer is in tension (k=1), while the inner portion of the bottom layer ( $\ell=1$ ) is in compression (k=2) and the outer portion of this layer in tension (k=1). Summarizing, the four regions are as follows:

Layer	Region	Fiber-Direction Tension or Compression		
l = 2	- h/2 to z <sub>ny</sub>	Compression (k=2)		
e = 2	z <sub>ny</sub> to 0	Tension (k=1)		
e = 1	0 to z <sub>nx</sub>	Compression (k=2)		
2 = 1	z <sub>nx</sub> to h/2	Tension (k=1)		

It is noted that it is assumed that the x-direction neutral-surface location  $z_{nx} \ge 0$ , while the y-direction one  $(z_{ny})$  is negative.

Thus, the integral for A  $_{ij}$  in Eqs. (5) is subdivided into four regions, in each of which the plane-stress reduced stiffnesses  $\textbf{Q}_{ijk\ell}$  are constant.

$$A_{ij} = \int_{-h/2}^{z_{ny}} Q_{ij22} dz + \int_{z_{ny}}^{0} Q_{ij12} dz + \int_{0}^{z_{nx}} Q_{ij21} dz + \int_{z_{nx}}^{h/2} Q_{ij11} dz$$

$$= (Q_{ij11} + Q_{ij22})(h/2) + (Q_{ij21} - Q_{ij11})z_{nx} + (Q_{ij22} - Q_{ij12})z_{ny}$$
(A1)

Introducing  $Z_x = z_{nx}/h$  and  $Z_y = z_{ny}/h$ , one obtains

$$A_{ij}/h = (1/2)(Q_{ij22} + Q_{ij11}) + (Q_{ij21} - Q_{ij11})Z_x + (Q_{ij22} - Q_{ij12})Z_y$$
 (A2)

In similar fashion, the next two integrals in Eqs. (5) become

$$4B_{ij}/h^2 = (1/2)(Q_{ij11} - Q_{ij22}) + 2(Q_{ij21} - Q_{ij11})Z_x^2 + 2(Q_{ij22} - Q_{ij12})Z_y^2$$
 (A3)

$$12D_{ij}/h^{3} = (1/2)(Q_{ij_{11}} + Q_{ij_{22}}) + 4(Q_{ij_{21}} - Q_{ij_{11}})Z_{x}^{3} + 4(Q_{ij_{21}} - Q_{ij_{12}})Z_{y}^{3}$$
 (A4)

The expression for  $S_{i,i}/h$  is the same as for  $A_{i,i}/h$ , Eq. (A2).

To apply Eqs. (A2)-(A4) to a single-layer plate with the fibers oriented in the x direction, it is necessary to merely set  $Z_y=0$ . In deriving these equations, it was assumed that  $Z_x\geq 0$  and  $Z_y\leq 0$ . In the event that the final results obtained for  $Z_x$  and  $Z_y$  did not meet these conditions, obviously Eqs. (A2)-(A4) would not be valid, and it would become necessary to investigate another of the other three possible cases:

$$Z_x \ge 0$$
 and  $Z_y \ge 0$   
 $Z_x \le 0$  and  $Z_y \le 0$   
 $Z_x \le 0$  and  $Z_y \ge 0$ 

Fortunately, however, in all of the static problems treated here, the conditions for the case derived in this appendix are satisfied.

## Appendix B: Reduction of Closed-Form Solution for Single-Layer Transversely Isotropic Material

In order to obtain simple, concise expressions for the neutral-surface location and the deflection, the closed-form equations given in the body of the paper are reduced to the special case of a square plate made of a transversely isotropic bimodulus material with an inplane Poisson's ratio of zero.

Then

$$A_{11} = A_{22} = A$$
,  $A_{12} = 0$ ,  $A_{66} = A/2$   
 $B_{11} = B_{22} = B$ ,  $B_{12} = 0$ ,  $B_{66} = B/2$   
 $D_{11} = D_{22} = D$ ,  $D_{12} = 0$ ,  $D_{66} = D/2$   
 $S_{44} = S_{55} = S$ ,  $S_{45} = 0$  (B1)

Now Eqs. (15) reduce to the following, since  $\beta = \alpha$ :

$$C_{11} = (3/2)A\alpha^2$$
,  $C_{12} = (1/2)A\alpha^2$ ,  $C_{13} = 0$   
 $C_{14} = (1/2)B\alpha^2$ ,  $C_{15} = (3/2)B\alpha^2$ ,  $C_{ji} = C_{ij}$ ,  
 $C_{22} = C_{11}$ ,  $C_{23} = 0$ ,  $C_{24} = C_{15}$ ,  $C_{25} = C_{14}$ , (B2)  
 $C_{33} = 2K^2S\alpha^2$ ,  $C_{34} = K^2S\alpha$ ,  $C_{35} = C_{34}$ ,  
 $C_{44} = (3/2)D\alpha^2 + K^2S$ ,  $C_{45} = (1/2)D\alpha^2$ ,  $C_{55} = C_{44}$ 

The biaxial symmetry of this special case requires

$$b = a, \beta = \alpha, V = U, Y = X, z_{nx} = z_{ny} = z_n$$
 (B3)

Using Eqs. (B2) and (B3) in the first two of Eqs. (14), one finds that for this special case

$$z_{nx} = z_{ny} = B/A = z_n \tag{B4}$$

Using the fourth equation of Eqs. (14), one obtains

$$X/W = \frac{-K^2S\alpha}{2(D-BZ_n)\alpha^2 + K^2S}$$
 (B5)

It is noted that the bending slope vanishes for both S = 0 and 1/S = 0.

Finally, the third of Eqs. (14) yields

$$W = \frac{q_0}{4(D-Bz_n)\alpha^4} [1 + 2(D-Bz_n)(\alpha^2/K^2S)]$$
 (B6)

It is seen that the quantity in front of the first bracket on the right side of Eq. (B6) is equal to the deflection of a thin isotropic plate. The second term inside the brackets is the fractional increase in deflection due to thickness-shear deformation, which obviously increases as  $G_z$  is decreased. The quantity D-Bz<sub>n</sub> is the so-called reduced stiffness, first obtained for laminated, isotropic thin plates by Pister<sup>15</sup>.

For the present case, Eqs. (A2)-(A4) become

$$A/h = \bar{Q} + Z\Delta Q$$
 ,  $4B/h^2 = -(1/2)\Delta Q (1-4Z^2)$  (B7)  
 $12D/h^3 = \bar{Q} + 4Z^3\Delta Q$ 

Here

$$\bar{Q} = (1/2)(Q_c + Q_t)$$
 ,  $\Delta Q = Q_c - Q_t$  (B8)

Combining Eqs. (B4) and (B7), one obtains the following quadratic expression for Z:

$$Z = -(\bar{Q}/\Delta Q) + [(\bar{Q}/\Delta Q)^2 - (1/4)]^{\frac{1}{2}}$$
 (B9)

A1so

$$S/h = (1/2)(G_{zc}+G_{zt}) + Z(G_{zc}-G_{zt})$$
 (B10)

## Appendix C: Method of Estimating Transverse-Thickness Shear Moduli

In the tests reported by Patel et al.<sup>3</sup>, only inplane compliances were measured. Thus, it is necessary to estimate the values for the thickness-shear moduli, which are needed for the thick-plate analysis.

It is believed to be a reasonable engineering assumption to assume that an individual composite-material layer is transversely isotropic with the plane of isotropy being the cross-sectional plane, i.e., the plane normal to the fibers. Thus, it follows that the longitudinal-thickness shear modulus  $(\mathsf{G}_{13})$  is equal to the inplane (longitudinal-transverse) shear modulus  $(\mathsf{G}_{12})$ .

Estimation of the other thickness-shear modulus is more complicated. One can use the well-known isotropic relation for the transverse-thickness shear modulus  $G_{23}$  in terms of the thickness Young's modulus  $E_3$  and transverse-thickness Poisson's ratio  $v_{23}$  provided the latter two quantities are known:

$$G_{23k} = E_{3k}/[2(1+v_{23k})]$$
 (C1)

In view of the transverse-isotropy assumption mentioned above, it can be assumed that  $E_{3k} = E_{2k}$ , which was obtained from the inplane tests.

Foye<sup>16</sup> presented a relation for  $\nu_{23}$  which can be rewritten in the following form, which is more convenient for the present purpose:

$$v_{23k} = v_{12k} + \frac{\left[ \left( v_m / E_m \right) - \left( v_f / E_f \right) \right] v_m (1 - v_m)}{1 - v_m^2} + \frac{1}{E_f V_f} - \frac{v_m}{E_m} \frac{v_f}{E_f}$$
 (C2)

It is noted that Ref. 3 provided data for  $E_f$ ,  $E_m$ , and  $V_f$ . It is reasonable to use a value of 0.499 for  $v_m$  of rubber. Thus, the only unknown quantity on the right side of Eq. (C2) is  $v_f$ , which could be computed from

the following rule-of-mixtures expression for  $v_{12k}$ , which is known to be very accurate for polymer-matrix composites:

$$v_{12k} = v_{fk} V_f + v_m (1 - V_f)$$
 (C3)

The rule-of-mixtures expression for the longitudinal Young's modulus is also known to be accurate for polymer-matrix composites:

$$E_{1k} = E_{fk}V_f + E_m(1-V_f)$$
 (C4)

Unfortunately, however, for the data of Ref. 3, the measured values of  $E_{1t}$  (tension) were <u>higher</u> than predicted by Eq. (C4). Thus, it was decided to use Eq. (C4) to obtain an effective fiber volume fraction  $V_f^*$ , and then to use this effective value to predict  $E_{fc}$  (compression) and  $v_{ft}$  and  $v_{fc}$ . However, using either  $V_f$  or  $V_f^*$  in Eq. (C3), one obtains negative  $v_{ft}$  and  $v_{ft}$  values, which are not reasonable physically. Thus, it was assumed that due to the loose nature of the cord, that it was not restrained by the matrix. Thus, instead of obtaining  $v_{fk}$  from Eq. (C3), it was obtained from

$$v_{fk} = v_{12k}/V_f^* \tag{C5}$$

Sample calculations for aramid-rubber in compression are as follows. From Eq. (C4) for k = t:

$$V_f^* = (E_{1t} - E_m)/(E_{ft} - E_m) = (3.58 - 0.0080)/(24.8 - 0.0080) = 0.144$$

Then, using Eq. (C4) for k = c:

$$E_{fc} = [E_{1c} - E_{m}(1-V_{f}^{*})]/V_{f}^{*} = [0.00120 - 0.0080(0.856)]/0.144$$
  
= 0.0358 GPa

From Eq. (C5) with k = c,

$$v_{fc} = v_{12c}/v_{f}^{*} = 0.205/0.144 = 1.42$$

Using Eq. (C2), one obtains  $v_{23c} = 0.202$ 

Finally, from Eq. (C1),  $G_{23C} = 0.00499$  GPa

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ANALYSIS OF THICK RECTANGULAR PLA OF BIMODULUS COMPOSITE MATERIALS	Technical Report No. 11 6. PERFORMING ORG. REPORT NUMBER	
7. Author(*) C.W. Bert, J.N. Reddy, V.S. Reddy W.C. Chao	NOO014-78-C-0647	
School of Aerospace, Mechanical a Engineering University of Oklahoma, Norman, O	NR 064-609	
Department of the Navy, Office of Structural Mechanics Program (Cod Arlington, Virginia 22217	January 1980  IS. NUMBER OF PAGES 29	
14. MONITORING AGENCY NAME & ADDRESS(If different	from Controlling Office)	UNCLASSIFIED  15. DECLASSIFICATION/ DOWNGRADING SCHEDULE

#### 16. DISTRIBUTION STATEMENT (of this Report)

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17. DISTRIBUTION STATEMENT (of the abstract entered in Block 20, if different from Report's

#### 18. SUPPLEMENTARY NOTES

This paper will appear in the Proceedings of the AIAA/ASME/ASCE/AHS 21st Structures, Structural Dynamics and Materials Conference, Seattle, Washington, May 12-14, 1980 (AIAA Paper 80-0685).

#### 19. KEY WORDS (Continue on reverse side if necessary and identify by block number)

Bimodulus materials, classical solution, closed-form solution, composite materials, fiber-reinforced materials, finite-element analysis, laminated plates, moderately thick plates, rectangular plates, shear flexible plate theory, static plate bending.

ABSTRACT (Continue on reverse elde if necessary and identify by block number)

A mixed finite-element analysis is presented for static behavior of rectangular plates having finite transverse shear moduli and different elastic properties depending upon whether or not the fiber-direction strains are tensile or compressive. As a benchmark to evaluate the validity and accuracy of the finite-element analysis, a closed-form solution is presented for the particular case of an unsymmetric-cross-ply plate having freely supported edges and subjected to a sinusoidally distributed normal-pressure loading.

DD , PORM 1473

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